图示

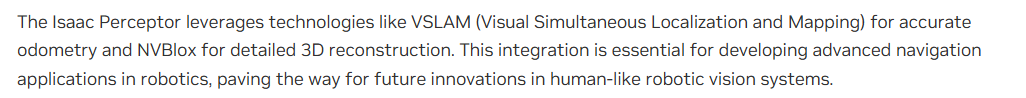
AI 生成的内容可能不正确。

文本

AI 生成的内容可能不正确。

文本, 日程表

AI 生成的内容可能不正确。

图形用户界面, 文本, 应用程序, 电子邮件

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Autonomous Mobile Robots (AMRs).

**Key Features**

* **Simulation-Based Training**: The model is trained using only simulation data, allowing for efficient development without physical trials.
* **Zero-Shot Deployment**: Successfully deployed in real-world environments like the Hubble Lab without additional training, demonstrating its adaptability.
* **Cross-Embodiment Capability**: Policies developed for AMRs are transferable to other robots, such as humanoid robots, quadrupeds, and space forklifts.

This model exemplifies the potential for cross-platform functionality in robotics, addressing complex computational challenges and paving the way for versatile applications.

Learn More: [X-Mobility: End-To-End Generalizable Navigation via World Modeling](https://arxiv.org/html/2410.17491v1)